

Participatory Air Pollution Monitoring Using Smartphones

ETH

Hönggerische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

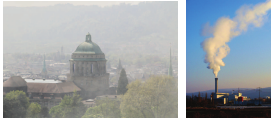
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TIK

Technische Information und Kommunikationsnetze
Computer Engineering and Networks Laboratory

Goals

Increase public awareness of urban air pollution



Air pollution in the city of Zurich

Involve general public into environmental monitoring



Participants of a flash mob

Improve temporal and spatial resolution of current air pollution maps



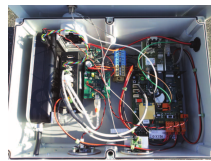
Ozone concentration levels

Autonomous Sensing

Data collection using mobile sensor nodes on top of trams:

- Sensors: O₃, CO, and PM
- Localization: GPS
- Communication: GSM and WLAN
- Processing: Gumstix

Provides initial coverage of the area of interest



Sensor box with low-cost sensors



Five sensor boxes on top of trams

Participatory Sensing

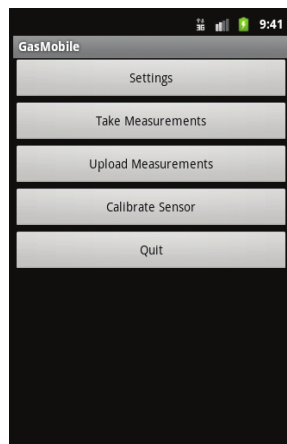
Data collection using off-the-shelf smartphones:

- Sensors: O₃ and CO
- Localization: GPS
- Communication: GSM and WLAN
- Processing: Smartphone

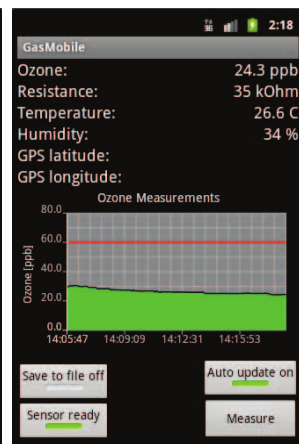
The average citizen senses the air she breathes



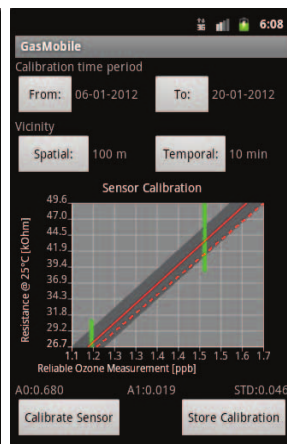
Low-cost ozone sensor connected to a HTC Hero



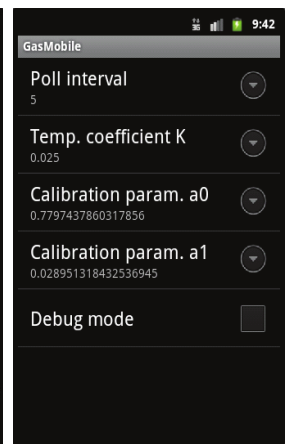
Main menu



Sensing



Calibration



Settings

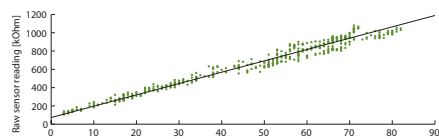
Ozone Sensor

Tin dioxide ozone sensor:

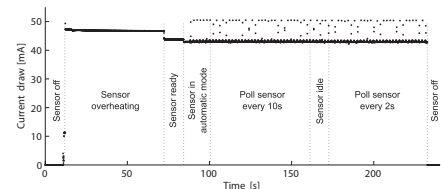
- Resistance of the tin dioxide (SnO₂) layer depends on the ozone concentration
- Sensing range between 0 ppb and 200 ppb



Ozone sensor



Response curve is quasi-linear with respect to the ozone concentration



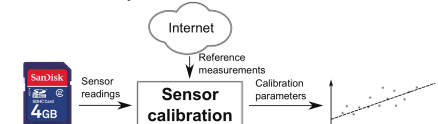
Current draw of the ozone sensor over time

Support High Data Quality

Users must assume a certain data quality:

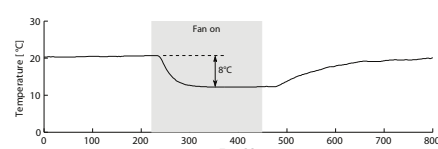
- Assistance in sensor calibration
- Advice when to perform measurements depending on motion speed

Calibration procedure:



Measurements near a reference station are used to update calibration

Effect of mobility on sensor readings:



Air flow generated by a fan influences the on-board temperature

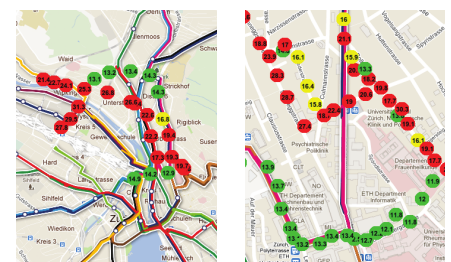
- The temperature drop induces a maximum error of 14%

Measurement Campaign

Air pollution monitoring in an urban area:

- Ozone sensor mounted on a bicycle
- Sampling interval of 5 seconds, in total more than 2,500 measurements in Zurich

Ozone pollution maps with high spatial resolution:



Overview

Close-up view

- The measurement error is on average 2.74 ppb when compared to high-quality stations