

Exploring Facial Nerve Detection Accuracy with a Novel Electrode Design in an In-Vivo Model

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Introduction

Minimally invasive direct cochlear access (DCA) is a computer assisted robotic approach to cochlear implantation [1]. The lack of direct visual control of the tool position puts structures such as the facial nerve (FN) at risk. Recently, neuromonitoring technology was integrated into a commercially available drill system enabling real-time monitoring of the FN [2]. Our group evaluated the feasibility of using this system combined with our robotic approach in a live sheep study [3]. The results of this study showed that the current implementation is neither sensitive nor specific enough to provide useful information during DCA procedures. This abstract reports on our initial efforts to optimize a stimulating electrode with the aim of detecting the FN within a very narrow distance range.

Materials & Methods



- A stainless steel rod (Ø 1 mm) forms a flat cathode at the tip and is the core of the probe.
- A standard shrink tube insulates the rod from the anode ring. •
- A configurable anode ring (1 x Ø 1.8 mm) of stainless steel is placed around the shrink tube. •
- Different distances from the anode to the cathode can be configured (e.g. d = 8 and d = 3). •
- An insulated wire (copper) contacts the stainless steel ring. •

- 2 rain worms were anesthetized using a 10% ethanol bath during 10 min.
- A cortical segment of bovine tibia was prepared with a channel simulating the fallopian canal.

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- 4 tunnels were drilled with different distances to the canal (1, 0.5, 0.25, 0 mm).
- The bone was held in place directly contacting the worm by using a laboratory adjustable arm.
- The probe was placed in each tunnel and the stimulation protocol was applied.



Results



- Fig. 5: Stimulus threshold curves for concentric probe d=3 mm •
- For the case at 1 mm distance, responses were only observed for pulses of duration greater than 150 µs. For cases <0.5 mm distance, responses were observed for all pulse durations tested.

differentiate between distances 0.25 and 0.5 mm.

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The concentric probe, d = 3 mm, was most selective.

The monopolar probe was sensitive for all distances, but • exhibited low selectivity for distances above 0.25 mm.

The concentric probe, d = 8 mm, was sensitive, but could not

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Conclusions	References
A bovine bone / earthworm model was successfully implemented to test the effect of inter-electrode distance in a concentric stimulation probe. 2 concentric (d = 3, d = 8 mm) and 1 monopolar configuration were tested in 1 bone sample and 2 different worms. The concentric stimulation presented the best spatial selectivity for all tested pulse durations, with the d = 3 mm	[1] Bell et al., "In Vitro Accuracy Evaluation of Image-Guided Robot System for Direct Cochlear Access.," <i>Otol. Neurotol.</i> , 2013.
configuration showing best overall selectivity for pulse durations greater than 100 µs.	[2] Bernardeschi et al., "Continuous facial nerve stimulating burr for otologic surgeries.," <i>Otol. Neurotol.</i> , 2011.
One of the main limitations found during this preliminary study was the inability to monitor the contact of the bone sample with the worm body. Secondly, in this study a primitive probe geometry was used: future studies will implement a stimulation probe	[3] Ansó at al. "Eassibility of Using EMC for Early Dotaction of the Escial
which will precisely fit into the DCA tunnel. Work is also underway to automate the stimulation protocol using a configurable system which will enable the protocol to be extended to cover more stimulation parameters, and increase the sample size for	Nerve During Robotic Direct Cochlear Access." Otol. Neurotol., 2014.
improved statistical validity. Finally, inter-electrode impedance measurements are also being implemented to determine its effect on stimulation efficacy.	[4] Yoshida et al., "Experimental validation of the nerve conduction velocity selective recording technique using a multi-contact cuff electrode.," <i>Med. Eng. Phys.</i> , 2009.